

XDP - eXpress Data Path

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Intro: What is XDP?

Really, don't everybody know what XDP is by now?!

- XDP = eXpress Data Path

Basically: New layer in the kernel network stack

- Before allocating the SKB
 - Driver level hook at DMA level
- Means: Competing at the same "layer" as DPDK / netmap
- Super fast, due to
 - Take action/decision earlier (e.g. skip some network layers)
 - No-memory allocations
- Not kernel bypass, data-plane is kept inside kernel
 - via BPF: makes early network stack run-time programmable
 - Cooperates with kernel



Fast and programmable networking

You have access to these new super powers!

You as Linux users are in control

- Via uploading a BPF program
- You get early access to raw packets
 - Both read and modify
- Take early action
 - Perfect for DDoS protection
 - Facebook use it for Load-Balancing
- The limit is your imagination
 - Within BPF and hook limitation
 - ... and kernel community is open to support new use-cases



Intro: XDP: data-plane and control-plane

Overall design

<u>Data-plane:</u> inside kernel, split into:

- Kernel-core: Fabric in charge of moving packets quickly
- In-kernel BPF program:
 - Policy logic decide action
 - Read/write access to packet

Control-plane: Userspace

- Userspace load BPF program
- Can control program via changing BPF maps
- Everything goes through bpf system call



Intro: XDP actions and cooperation

What are the basic building blocks I can use?

BPF program return an action or verdict

XDP_DROP, XDP_PASS, XDP_TX, XDP_ABORTED, XDP_REDIRECT

How to cooperate with network stack

- Pop/push or modify headers: Change RX-handler kernel use
 - e.g. handle protocol unknown to running kernel
- Can propagate 32Bytes meta-data from XDP stage to network stack
 - TC (clsbpf) hook can use meta-data, e.g. set SKB mark



Intro: Why developers should love BPF

How BPF avoids creating a new kernel ABI for every new user-invented policy decision?

BPF is sandboxed code running inside kernel (XDP only loaded by root)

- A given kernel BPF hook just define:
 - possible actions and limit helpers (that can lookup or change kernel state)

Users get programmable policies (within these limits)

- Userspace "control-plane" API tied to userspace app (not kernel API)
 - likely via modifying a BPF-map
- No longer need a kernel ABI
 - like sysctl/procfs/ioctls etc.



Getting started with XDP

How do you find some example code...

Use LLVM / clang compiler

- Write code in restricted C
 - BPF have some limitations to guarantee safely

Look at examples

- Kernel source dir: samples/bpf/
- My github repo
 - https://github.com/netoptimizer/prototype-kernel/
 - Directory: kernel/samples/bpf/



End slide

... Questions?



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